Amendments to the Specification

Please amend p. 13, II. 7-18, of the specification as filed as follows:

Axial movement of the platform is effected by a worm drive screw mechanism 19 (shown more clearly in FIG. 4). This comprises a two-piece shaft 25, 27 and actuator 21. The two sections of the shaft are screwed together by respective internal and external threads on shafts 27 and 25 25 and 27. Shaft [[27]] 25 is fixed to underside 11b of the platform 11. Shaft [[25]] 27 is fixed to actuator 21 by a screw fastening fastened [[(]] in an opposite direction from that [[joins]] joining shafts 25 and 27[[)]]. Turning the screw actuator 21 in one direction advances the platform 11 a set distance upward within the reservoir. In this way the reservoir volume is decreased and the fluid forced to exit via the dispensing orifices.